Module 3

Technology inzetten voor het automatisch rijden

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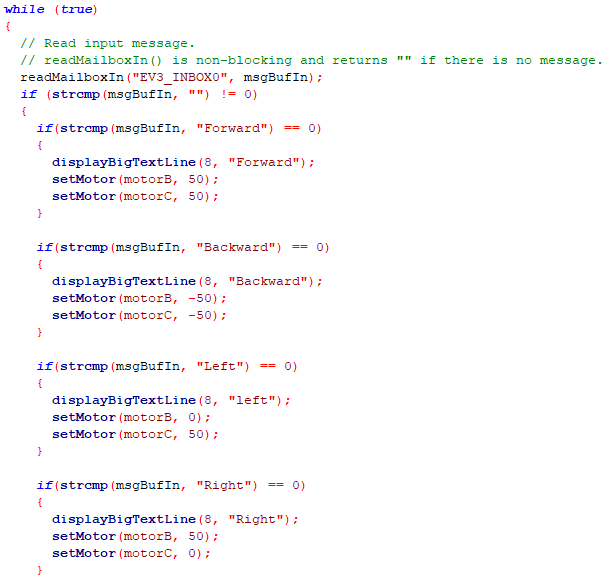
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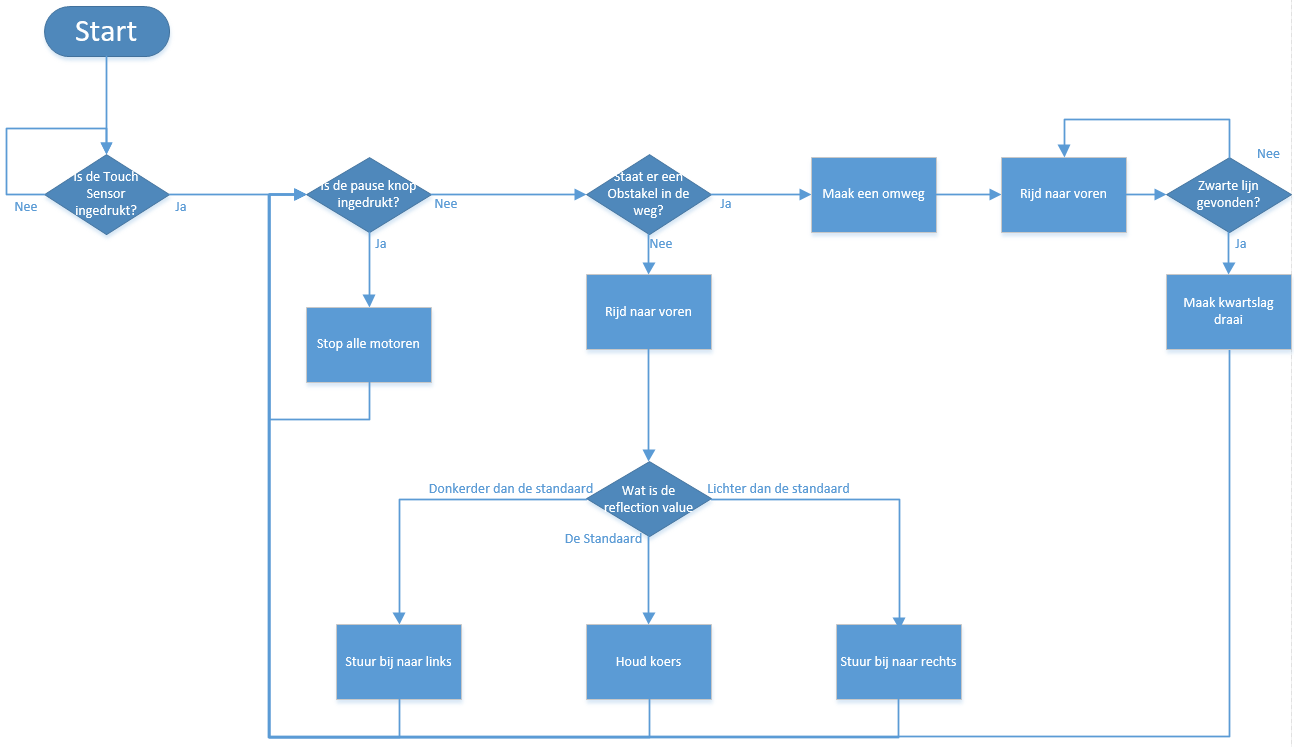
# Module 2.1

## Code



# Module 2.2 – 2.5

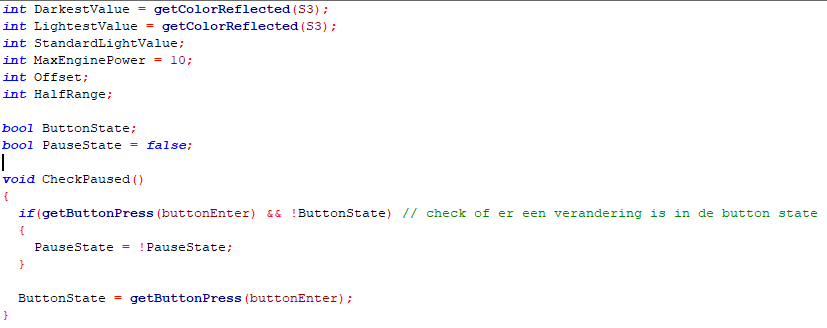
## Flow-Chart



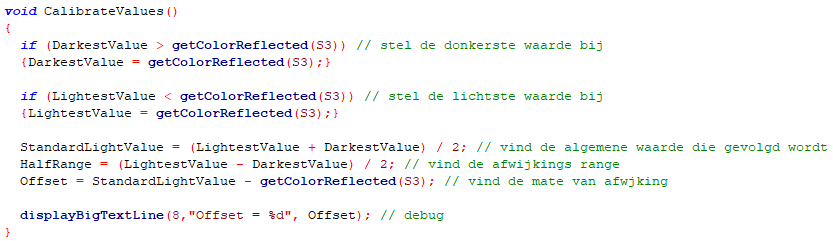
Link voor betere Weergave: <https://drive.google.com/open?id=1mMaBmnQnCb5VIEaaypnY8kOFj9mnrW-c>

## Code:

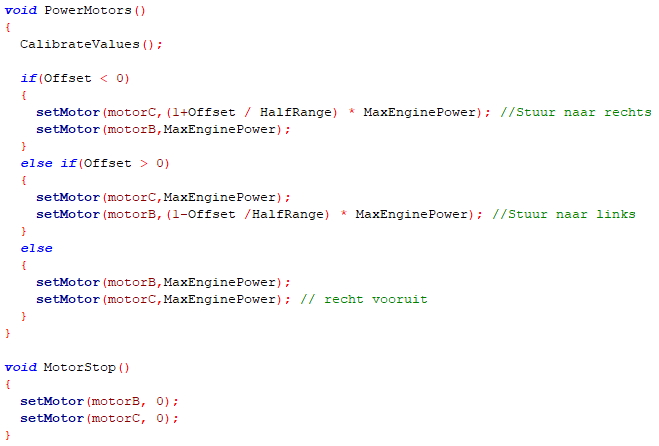
### Variabelen en CheckPaused Method



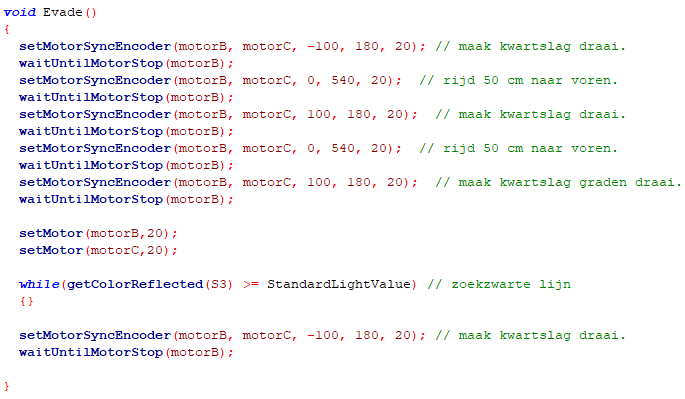
### CalibrateValues Method



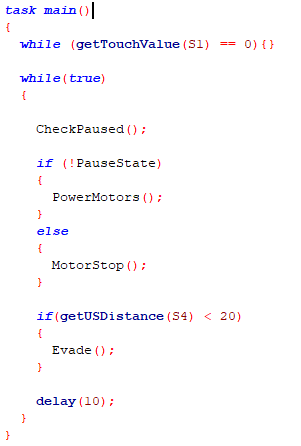
### PowerMotors + StopMotors Method



### Evade Method



### Main Method



# Bronnen

<https://www.youtube.com/watch?v=BjVeWRNiddE>

<https://stackoverflow.com/questions/16627588/what-is-the-correct-string-terminator-in-c>

<https://www.tutorialspoint.com/cprogramming/c_arrays.htm>

<https://www.le.ac.uk/users/rjm1/cotter/page_22.htm>

<https://www.tutorialspoint.com/cprogramming/c_variables.htm>

<https://www.geeksforgeeks.org/understanding-extern-keyword-in-c/>

<https://stackoverflow.com/questions/15707732/what-does-array-means>